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Joint work with

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Program

- Introduction
- Sonneveld spaces
- Inducing dimension reduction
- IDR and deflation

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- Introduction
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Solve Ax = b for x. A is $n \times n$ non-singular (complex).

To solve $\mathbf{A}\mathbf{x} = \mathbf{b}$ for \mathbf{x}

• Expansion.

Built a Krylov subspace $\mathcal{K}_k(\mathbf{A}, \mathbf{b})$

• Extraction.

Extract an approximate solution \mathbf{x}_k from $\mathcal{K}_k(\mathbf{A}, \mathbf{b})$

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Convergence depends on angle **b** and $A\mathcal{K}_k(A, b)$

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Convergence depends on spectral properties of A:

- how well eigenvalues are clustered
- on the "conditioning" of the eigenvector basis

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Extraction quality depends on specific method

practical issues as efficiency, stability

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Two ways to improve spectral properties:

- Preconditioning.
- Deflation.

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Apply iterative method to $\mathbf{K}^{-1}\mathbf{A}\mathbf{x} = \mathbf{K}^{-1}\mathbf{b}$

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Remove known components

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- **Preconditioning**. To cluster eigenvalues, . . . Apply iterative method to $\mathbf{K}^{-1}\mathbf{A}\mathbf{x} = \mathbf{K}^{-1}\mathbf{b}$
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Two ways to improve spectral properties:

- **Preconditioning**. To cluster eigenvalues, ... Apply iterative method to $\mathbf{K}^{-1}\mathbf{A}\mathbf{x} = \mathbf{K}^{-1}\mathbf{b}$
- Deflation. To replace small eigenvalues by 0 Remove known components

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 $s \in \mathbb{N}$, typically s = 1, 2, 4, 8. $\widetilde{\mathbf{R}}$ is a full rank $n \times s$ matrix.

Terminology. $\widetilde{\mathbf{R}}$ is called

the initial shadow residual or

the **IDR test matrix**

- $s \in \mathbb{N}$, typically s = 1, 2, 4, 8. $\widetilde{\mathbf{R}}$ is a full rank $n \times s$ matrix. **Definition**.
- Block Krylov subspace of order k generated by \mathbf{A}^* and $\widetilde{\mathbf{R}}$

$$\mathcal{K}_k(\mathbf{A}^*, \widetilde{\mathbf{R}}) \equiv \left\{ \sum_{j < k} (\mathbf{A}^*)^j \, \widetilde{\mathbf{R}} \, \gamma_j \mid \gamma_j \in \mathbb{C}^s
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Example.

Bi-CG generates residuals $\mathbf{r}_{k}^{\text{Bi-CG}} \perp \mathcal{K}_{k}(\mathbf{A}^{*}, \tilde{\mathbf{r}}_{0})$, here $\widetilde{\mathbf{R}} = [\widetilde{\mathbf{r}}_{0}]$:

$$\mathbf{r}_{k+1}^{\text{Bi-CG}} = \mathbf{r}_{k}^{\text{Bi-CG}} - \mathbf{A}\mathbf{u}_{k}\alpha_{k} \perp \mathcal{K}_{k+1}(\mathbf{A}^{*}, \widetilde{\mathbf{r}}_{0})$$

with \mathbf{u}_k such that $\mathbf{A}\mathbf{u}_k \perp \mathcal{K}_k(\mathbf{A}^*, \widetilde{\mathbf{r}}_0)$.

- $s \in \mathbb{N}$, typically s = 1, 2, 4, 8. $\widetilde{\mathbf{R}}$ is a full rank $n \times s$ matrix. **Definition**. P_k polynomial of exact degree k.
- P_k Sonneveld subspace order k generated by A and $\widetilde{\mathbf{R}}$

$$\mathcal{S}(P_k, \mathbf{A}, \widetilde{\mathbf{R}}) \equiv \left\{ P_k(\mathbf{A}) \, \mathbf{v} \mid \mathbf{v} \perp \mathcal{K}_k(\mathbf{A}^*, \widetilde{\mathbf{R}}) \right\}$$

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Example. $\widetilde{\mathbf{R}} = [\widetilde{\mathbf{r}}_0], \quad \mathbf{r}_k^{\text{Bi-CGSTAB}} = P_k(\mathbf{A})\mathbf{r}_k^{\text{Bi-CG}}$

Note that $\mathbf{r}_{k}^{\text{Bi-CG}} \perp \mathcal{K}_{k}(\mathbf{A}^{*}, \tilde{\mathbf{r}}_{0})$. In **Bi-CGSTAB**: $P_{k+1}(\lambda) = (1 - \omega_{k}\lambda)P_{k}(\lambda)$, where, with $\mathbf{r}_{k}' \equiv P_{k}(\mathbf{A})\mathbf{r}_{k+1}^{\text{Bi-CG}}$, $\omega_{k} \equiv \operatorname{argmin}_{\omega \in \mathbb{C}} \|\mathbf{r}_{k}' - \omega \mathbf{A}\mathbf{r}_{k}'\|_{2}$ **Theorem**. $\mathbf{r}_{k}^{\text{Bi-CGSTAB}} \in \mathcal{S}(P_{k}, \mathbf{A}, \tilde{\mathbf{r}}_{0})$. $s \in \mathbb{N}$, typically s = 1, 2, 4, 8. $\widetilde{\mathbf{R}}$ is a full rank $n \times s$ matrix. **Definition**. P_k polynomial of exact degree k.

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[Sonneveld, van Gijzen, 2008, S. Sonneveld, van Gijzen 2010]

Property. Bi-CGSTAB ~ IDR(s) for s = 1 (i.e. $\mathbf{R} = [\tilde{\mathbf{r}}_0]$)



 $u_{xx} + u_{yy} + u_{zz} + 1000 u_x = f, \quad f \text{ is defined by the solution}$ $u(x, y, z) = \exp(xyz)\sin(\pi x)\sin(\pi y)\sin(\pi z).$

Discretized with (10 \times 10 \times 10) volumes. No preconditioning.



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IDR Theorem. With $P_{k+1}(\lambda) \equiv (\alpha - \omega\lambda)P_k(\lambda), \ \omega \neq 0$

• $(\alpha \mathbf{I} - \omega \mathbf{A}) \left(\mathcal{S}(P_k, \mathbf{A}, \widetilde{\mathbf{R}}) \cap \widetilde{\mathbf{R}}^{\perp} \right) = \mathcal{S}(P_{k+1}, \mathbf{A}, \widetilde{\mathbf{R}})$

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$$\mathcal{S}(P_{k+1}, \mathbf{A}, \widetilde{\mathbf{R}}) \subset \mathcal{S}(P_k, \mathbf{A}, \widetilde{\mathbf{R}})$$

• \subseteq_{\neq} if **A** has no eigenvector in $\widetilde{\mathbf{R}}^{\perp}$ and $\mathcal{S}(P_k, \mathbf{A}, \widetilde{\mathbf{R}}) \neq \{\mathbf{0}\}$.

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If zeros $P_{k+1} \neq$ eigenvalues **A**, then, increase k leads to dimension reduction $S(P_k, \mathbf{A}, \widetilde{\mathbf{R}}) =$ dimension increase $\mathcal{K}_k(\mathbf{A}^*, \widetilde{\mathbf{R}})$

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 $\begin{array}{ll} \textbf{Corollary} & \mathcal{G}_k \equiv \mathcal{S}(P_k, \textbf{A}, \widetilde{\textbf{R}}), & \mathcal{G}'_k \equiv \mathcal{G}_k \cap \textbf{R}^{\perp}. \end{array}$ $\text{With } P_{k+1}(\lambda) \equiv (1 - \omega_k \lambda) P_k(\lambda), \text{ we have}$ $\mathcal{G}_{k+1} \equiv (I - \omega_k \textbf{A}) \mathcal{G}'_k \subset \mathcal{G}_k \quad \text{and} \quad \textbf{A} \mathcal{G}'_k \subset \mathcal{G}_k \end{array}$

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$$(\omega_k)$$
, $\widetilde{\mathbf{R}}$. Let $P_{k+1}(\lambda) = (1 - \omega_k \lambda) P_k(\lambda)$.
 $\mathcal{G}_0 = \mathbb{C}^n$, $\mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_k \mathbf{A}) \mathcal{G}'_k$ with $\mathcal{G}'_k \equiv \mathcal{G}_k \cap \widetilde{\mathbf{R}}^{\perp}$

IDR: construct residuals \mathbf{r}_k in \mathcal{G}_k iteratively by increase k

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IDR: construct residuals \mathbf{r}_k in \mathcal{G}_k

The first residual to be in \mathcal{G}_k by construction is called a **primary residual**.

The implementation may rely on other residuals: secondary residuals

Select (ω_k) , $\widetilde{\mathbf{R}}$. Let $P_{k+1}(\lambda) = (1 - \omega_k \lambda) P_k(\lambda)$. $\mathcal{G}_0 = \mathbb{C}^n$, $\mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_k \mathbf{A}) \mathcal{G}'_k$ with $\mathcal{G}'_k \equiv \mathcal{G}_k \cap \widetilde{\mathbf{R}}^{\perp}$.

IDR: construct residuals \mathbf{r}_k in \mathcal{G}_k

All our updates for residuals are of the form

 $\mathbf{r} \leftarrow \mathbf{r} - \alpha \mathbf{c}$ with $\mathbf{c} = \mathbf{A}\mathbf{u}$ and \mathbf{u} available. Hence, $\mathbf{x} \leftarrow \mathbf{x} + \alpha \mathbf{u}$. Updates \mathbf{r} and \mathbf{x} are **consistent**.

Approximate solution x gets a(n almost) free ride: only vector updates, <u>no</u> MVs, <u>no</u> inner products.

Focuss on r

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IDR: $\mathbf{r}_k \in \mathcal{G}_k$, then construct residual \mathbf{r}_{k+1} in \mathcal{G}_{k+1}

$$\begin{array}{cccc} \text{IDR step} & & \text{pol. step} \\ \mathcal{G}_k & \rightarrow & \mathcal{G}'_k \equiv \mathcal{G}_k \cap \widetilde{\mathbf{R}}^\perp & \rightarrow & \mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_k \mathbf{A}) \mathcal{G}'_k \\ \mathbf{r}_k & & \Pi_1 & \mathbf{r}'_k = \Pi_1 \mathbf{r}_k & \mathbf{I} - \omega_k \mathbf{A} & \mathbf{r}_{k+1} = \mathbf{r}'_k - \omega_k \mathbf{A} \mathbf{r}'_k \end{array}$$

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 Π_1 is a skew projection that projects onto $\widetilde{\mathbf{R}}^{\perp}$

$$\Pi_1 = \mathbf{I} - \mathbf{V}\sigma^{-1}\widetilde{\mathbf{R}}^* \text{ with } \sigma \equiv \widetilde{\mathbf{R}}^*\mathbf{V} \quad s \times s \text{ non-singular,}$$

and $\mathbf{V} \equiv \mathbf{V}_k$ is $n \times s$ matrix with span $(\mathbf{V}) \subset \mathcal{G}_k$ $[\mathbf{r}_k, \mathbf{V}_k]$ full rank

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 $\Pi_1(\mathbf{v}_j) = 0$ for the columns of $\mathbf{V} = [\mathbf{v}_1, \dots, \mathbf{v}_s]$

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$$\mathbf{w}\in \mathcal{G}'_k \quad \Rightarrow \quad \mathbf{A}\mathbf{w}\in \mathcal{G}_k \quad \Rightarrow \quad \Pi_1\mathbf{A}\mathbf{w}\in \mathcal{G}'_k$$

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$$\begin{split} \mathbf{w} \in \mathcal{G}'_k &\Rightarrow \mathbf{A} \mathbf{w} \in \mathcal{G}_k &\Rightarrow \Pi_1 \mathbf{A} \mathbf{w} \in \mathcal{G}'_k \\ \Rightarrow & \mathcal{K}_{s+1}(\Pi_1 \mathbf{A}, \mathbf{r}'_k) \subset \mathcal{G}'_k \end{split}$$

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 $\mathcal{G}_0 = \mathbb{C}^n$, $\mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_k \mathbf{A}) \mathcal{G}'_k$ with $\mathcal{G}'_k \equiv \mathcal{G}_k \cap \widetilde{\mathbf{R}}^{\perp}$

IDR: construct residuals \mathbf{r}_{k+1} in \mathcal{G}_{k+1} , \mathbf{V}_{k+1} span in \mathcal{G}_{k+1} .

$$\begin{array}{cccc} \text{IDR step} & \text{pol. step} \\ \mathcal{G}_k & \rightarrow & \mathcal{G}'_k \equiv \mathcal{G}_k \cap \widetilde{\mathsf{R}} & \rightarrow & \mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_k \mathsf{A}) \mathcal{G}'_k \\ \mathbf{V}_k & \Pi_1 & \mathbf{V}'_k = ???? & \mathbf{I} - \omega_k \mathsf{A} & \mathbf{V}_{k+1} = \mathbf{V}'_k - \omega_k \mathsf{A} \mathbf{V}'_k \end{array}$$

$$\begin{split} \mathbf{w} \in \mathcal{G}'_k &\Rightarrow \mathbf{A} \mathbf{w} \in \mathcal{G}_k &\Rightarrow \Pi_1 \mathbf{A} \mathbf{w} \in \mathcal{G}'_k \\ \Rightarrow & \mathcal{K}_{s+1}(\Pi_1 \mathbf{A}, \mathbf{r}'_k) \subset \mathcal{G}'_k \end{split}$$

•
$$\mathbf{V}_k'$$
 with span $(\mathbf{r}_k', \mathbf{V}_k') = \mathcal{K}_{s+1}(\Pi_1 \mathbf{A}, \mathbf{r}_k')$

Select
$$(\omega_k)$$
, $\widetilde{\mathbf{R}}$. Let $P_{k+1}(\lambda) = (1 - \omega_k \lambda) P_k(\lambda)$.
 $\mathcal{G}_0 = \mathbb{C}^n$, $\mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_k \mathbf{A}) \mathcal{G}'_k$ with $\mathcal{G}'_k \equiv \mathcal{G}_k \cap \widetilde{\mathbf{R}}^{\perp}$

IDR: construct residuals \mathbf{r}_{k+1} in \mathcal{G}_{k+1} , \mathbf{V}_{k+1} span in \mathcal{G}_{k+1} .

$$\begin{array}{cccc} \text{IDR step} & \text{pol. step} \\ \mathcal{G}_k & \rightarrow & \mathcal{G}'_k \equiv \mathcal{G}_k \cap \widetilde{\mathsf{R}} & \rightarrow & \mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_k \mathsf{A}) \mathcal{G}'_k \\ \mathbf{V}_k & \Pi_1 & \mathbf{V}'_k = ???? & \mathbf{I} - \omega_k \mathsf{A} & \mathbf{V}_{k+1} = \mathbf{V}'_k - \omega_k \mathsf{A} \mathbf{V}'_k \end{array}$$

 Π_1 is a skew projection that projects onto $\widetilde{\textbf{R}}^{\perp}$

$$\begin{split} \mathbf{w} \in \mathcal{G}'_k &\Rightarrow \mathbf{A} \mathbf{w} \in \mathcal{G}_k &\Rightarrow \Pi_1 \mathbf{A} \mathbf{w} \in \mathcal{G}'_k \\ \Rightarrow & \mathcal{K}_{s+1}(\Pi_1 \mathbf{A}, \mathbf{r}'_k) \subset \mathcal{G}'_k \end{split}$$

• \mathbf{V}'_k with span $(\mathbf{r}'_k, \mathbf{V}'_k) = \mathcal{K}_{s+1}(\Pi_1 \mathbf{A}, \mathbf{r}'_k);$ \mathbf{AV}'_k is side product

Select
$$(\omega_k)$$
, $\widetilde{\mathbf{R}}$. Let $P_{k+1}(\lambda) = (1 - \omega_k \lambda) P_k(\lambda)$.
 $\mathcal{G}_0 = \mathbb{C}^n$, $\mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_k \mathbf{A}) \mathcal{G}'_k$ with $\mathcal{G}'_k \equiv \mathcal{G}_k \cap \widetilde{\mathbf{R}}^\perp$.

IDR: construct residuals \mathbf{r}_{k+1} in \mathcal{G}_{k+1} , \mathbf{V}_{k+1} span in \mathcal{G}_{k+1} .

$$\begin{array}{cccc} \text{IDR step} & \text{pol. step} \\ \mathcal{G}_k & \rightarrow & \mathcal{G}'_k \equiv \mathcal{G}_k \cap \widetilde{\mathsf{R}} & \rightarrow & \mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_k \mathbf{A}) \mathcal{G}'_k \\ \mathbf{V}_k & \Pi_1 & \mathbf{V}'_k = !! & \mathbf{I} - \omega_k \mathbf{A} & \mathbf{V}_{k+1} = \mathbf{V}'_k - \omega_k \mathbf{A} \mathbf{V}'_k \end{array}$$

Theorem. Assume span($[\mathbf{r}_k, \mathbf{V}_k]$) $\subset \mathcal{G}_k$. If $[\mathbf{r}'_k, \mathbf{V}'_k]$ spans $\mathcal{K}_{s+1}(\Pi_1 \mathbf{A}, \mathbf{r}'_k)$ and no break-down occurs, span($[\mathbf{r}_{k+1}, \mathbf{V}_{k+1}]$) $\subset \mathcal{G}_{k+1}$.

This is essentially the only way to move to the next \mathcal{G}_k

 $[\mathbf{r}'_k, \mathbf{V}'_k]$ spans $\mathcal{K}_{s+1}(\Pi_1 \mathbf{A}, \mathbf{r}'_k)$. How to select the basis \mathbf{V}_k ?

(In exact arithmetic)

any basis leads to the same projection.

Program

- Introduction
- Sonneveld spaces
- Inducing dimension reduction
- IDR and deflation

 $\begin{array}{ccc} \text{IDR step} & \mathcal{G}_k & \rightarrow & \mathcal{G}'_k \equiv \mathcal{G}_k \cap \widetilde{\textbf{R}}^{\perp} & \stackrel{\text{pol. step}}{\to} & \mathcal{G}_{k+1} \equiv (\textbf{I} - \omega_k \textbf{A}) \mathcal{G}'_k \\ \textbf{r}_k & \Pi_1 & \textbf{r}'_k = \Pi_1 \textbf{r}_k & \textbf{I} - \omega_k \textbf{A} & \textbf{r}_{k+1} = \textbf{r}'_k - \omega_k \textbf{A} \textbf{r}'_k \\ \Pi_1 = \textbf{I} - \textbf{A} \textbf{U} \sigma^{-1} \widetilde{\textbf{R}}^* \text{ with } \sigma \equiv \textbf{R}^* \textbf{A} \textbf{U} \text{ and } \textbf{V} = \textbf{A} \textbf{U} \\ \Pi_1 = \textbf{I} - \textbf{A} \textbf{Q} \text{ with } \textbf{Q} \equiv \textbf{U} \sigma^{-1} \widetilde{\textbf{R}}^* \end{array}$

IDR step

$$\mathcal{G}_{k} \xrightarrow{\rightarrow} \mathcal{G}_{k}^{\prime} \equiv \mathcal{G}_{k} \cap \widetilde{\mathbf{R}}^{\perp}$$
 pol. step
 $\mathbf{r}_{k} \xrightarrow{\Pi_{1}} \mathbf{r}_{k}^{\prime} \equiv \mathcal{G}_{k} \cap \widetilde{\mathbf{R}}^{\perp}$ $\overrightarrow{\mathbf{I}} \rightarrow \mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_{k} \mathbf{A}) \mathcal{G}_{k}^{\prime}$
 $\mathbf{r}_{k+1} = \mathbf{r}_{k}^{\prime} - \omega_{k} \mathbf{A} \mathbf{r}_{k}^{\prime}$
 $\Pi_{1} = \mathbf{I} - \mathbf{A} \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^{*}$ with $\sigma \equiv \mathbf{R}^{*} \mathbf{A} \mathbf{U}$ and $\mathbf{V} = \mathbf{A} \mathbf{U}$
 $\Pi_{1} = \mathbf{I} - \mathbf{A} \mathbf{Q}$ with $\mathbf{Q} \equiv \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^{*}$

Deflated system:

Solve
$$\Pi_1 \mathbf{A} \mathbf{x}' = \mathbf{r}'_k$$
 for $\mathbf{x}' \perp \widetilde{\mathbf{R}}$. (*)
Then $\mathbf{x} = \mathbf{x}_k + \mathbf{Q} \mathbf{r}_k + (\mathbf{I} - \mathbf{Q} \mathbf{A}) \mathbf{x}'$ solves $\mathbf{A} \mathbf{x} = \mathbf{b}$.
Note. $\Pi_1 \mathbf{A} : \widetilde{\mathbf{R}}^{\perp} \to \widetilde{\mathbf{R}}^{\perp}$ and $\Pi_1 \mathbf{r}_k \in \widetilde{\mathbf{R}}^{\perp}$.
 $\mathcal{K}_k(\Pi_1 \mathbf{A}, \Pi_1 \mathbf{r}_k)$ leads to approximate solutions of (*) in $\widetilde{\mathbf{R}}^{\perp}$.

IDR step

$$\mathcal{G}_{k} \xrightarrow{\rightarrow} \mathcal{G}_{k}' \equiv \mathcal{G}_{k} \cap \widetilde{\mathbf{R}}^{\perp} \xrightarrow{\text{pol. step}} \mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_{k} \mathbf{A}) \mathcal{G}_{k}'$$

 $\mathbf{r}_{k} \xrightarrow{\Pi_{1}} \mathbf{r}_{k}' \equiv \Pi_{1} \mathbf{r}_{k} \xrightarrow{\mathbf{I} - \omega_{k} \mathbf{A}} \mathbf{r}_{k+1} \equiv \mathbf{r}_{k}' - \omega_{k} \mathbf{A} \mathbf{r}_{k}'$
 $\Pi_{1} = \mathbf{I} - \mathbf{A} \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^{*} \text{ with } \sigma \equiv \mathbf{R}^{*} \mathbf{A} \mathbf{U} \text{ and } \mathbf{V} = \mathbf{A} \mathbf{U}$
 $\Pi_{1} = \mathbf{I} - \mathbf{A} \mathbf{Q} \text{ with } \mathbf{Q} \equiv \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^{*}$

Deflated system:

Solve
$$\Pi_1 \mathbf{A} \mathbf{x}' = \mathbf{r}'_k$$
 for $\mathbf{x}' \perp \widetilde{\mathbf{R}}$. (*)
Then $\mathbf{x} = \mathbf{x}_k + \mathbf{Q} \mathbf{r}_k + (\mathbf{I} - \mathbf{Q} \mathbf{A}) \mathbf{x}'$ solves $\mathbf{A} \mathbf{x} = \mathbf{b}$.
Note. $\Pi_1 \mathbf{A} : \widetilde{\mathbf{R}}^{\perp} \to \widetilde{\mathbf{R}}^{\perp}$ and $\Pi_1 \mathbf{r}_k \in \widetilde{\mathbf{R}}^{\perp}$.
 $\mathcal{K}_k(\Pi_1 \mathbf{A}, \Pi_1 \mathbf{r}_k)$ leads to approximate solutions of (*) in $\widetilde{\mathbf{R}}^{\perp}$.

Solve (*) with s steps of some Krylov method:

Advantage. At the same time a basis \mathbf{V}' of $\mathcal{K}_{s+1}(\Pi_1 \mathbf{A}, \Pi_1 \mathbf{r}_k)$ and a smaller residual.

IDR step

$$\mathcal{G}_{k} \xrightarrow{\rightarrow} \mathcal{G}_{k}^{\prime} \equiv \mathcal{G}_{k} \cap \widetilde{\mathbf{R}}^{\perp}$$
 $\mathbf{P}_{k} = \mathcal{G}_{k} \cap \widetilde{\mathbf{R}}^{\perp}$
 $\mathbf{P}_{k} = \mathbf{P}_{1}\mathbf{r}_{k}$
 $\mathbf{P}_{k} = \mathbf{P}_{1}\mathbf{r}_{k}$
 $\mathbf{P}_{k} = \mathbf{P}_{1}\mathbf{r}_{k}$
 $\mathbf{P}_{k} = \mathbf{P}_{k} - \omega_{k}\mathbf{A}\mathbf{r}_{k}^{\prime}$
 $\mathbf{P}_{1} = \mathbf{I} - \mathbf{A}\mathbf{U}\sigma^{-1}\widetilde{\mathbf{R}}^{*}$ with $\sigma \equiv \mathbf{R}^{*}\mathbf{A}\mathbf{U}$ and $\mathbf{V} = \mathbf{A}\mathbf{U}$
 $\mathbf{P}_{1} = \mathbf{I} - \mathbf{A}\mathbf{Q}$ with $\mathbf{Q} \equiv \mathbf{U}\sigma^{-1}\widetilde{\mathbf{R}}^{*}$

Deflated system:

Solve
$$\Pi_1 \mathbf{A} \mathbf{x}' = \mathbf{r}'_k$$
 for $\mathbf{x}' \perp \widetilde{\mathbf{R}}$. (*)
Then $\mathbf{x} = \mathbf{x}_k + \mathbf{Q} \mathbf{r}_k + (\mathbf{I} - \mathbf{Q} \mathbf{A}) \mathbf{x}'$ solves $\mathbf{A} \mathbf{x} = \mathbf{b}$.
Note. $\Pi_1 \mathbf{A} : \widetilde{\mathbf{R}}^{\perp} \to \widetilde{\mathbf{R}}^{\perp}$ and $\Pi_1 \mathbf{r}_k \in \widetilde{\mathbf{R}}^{\perp}$.
 $\mathcal{K}_k(\Pi_1 \mathbf{A}, \Pi_1 \mathbf{r}_k)$ leads to approximate solutions of (*) in $\widetilde{\mathbf{R}}^{\perp}$.

However, if \mathbf{s}_s is an *s*-step Krylov residual, then

$$\Pi_1(\mathbf{s}_s - \omega_k \mathbf{A} \mathbf{s}_s) = \mathbf{r}_{k+1}.$$

IDR step

$$\mathcal{G}_{k} \xrightarrow{\rightarrow} \mathcal{G}_{k}^{\prime} \equiv \mathcal{G}_{k} \cap \widetilde{\mathbf{R}}^{\perp}$$
 pol. step
 $\stackrel{\rightarrow}{\mathbf{r}_{k}} = \mathcal{G}_{k} \cap \widetilde{\mathbf{R}}^{\perp}$ $\stackrel{\rightarrow}{\mathbf{r}_{k}} = \mathbf{G}_{k+1} \equiv (\mathbf{I} - \omega_{k}\mathbf{A})\mathcal{G}_{k}^{\prime}$
 $\mathbf{r}_{k} = \mathbf{I}_{1}\mathbf{r}_{k}$ $\mathbf{I} - \omega_{k}\mathbf{A}$ $\mathbf{r}_{k+1} = \mathbf{r}_{k}^{\prime} - \omega_{k}\mathbf{A}\mathbf{r}_{k}^{\prime}$
 $\Pi_{1} = \mathbf{I} - \mathbf{A}\mathbf{U}\sigma^{-1}\widetilde{\mathbf{R}}^{*}$ with $\sigma \equiv \mathbf{R}^{*}\mathbf{A}\mathbf{U}$ and $\mathbf{V} = \mathbf{A}\mathbf{U}$
 $\Pi_{1} = \mathbf{I} - \mathbf{A}\mathbf{Q}$ with $\mathbf{Q} \equiv \mathbf{U}\sigma^{-1}\widetilde{\mathbf{R}}^{*}$

Interpretation. Solve Au = r

Search for an approximate solution in span(**U**)

 $\mathbf{R}^* \mathbf{A} \mathbf{U} \alpha = \mathbf{R}^* \mathbf{r}$ Then $\mathbf{u} \approx \mathbf{U} \alpha = \mathbf{U} (\mathbf{R}^* \mathbf{A} \mathbf{U})^{-1} \mathbf{R}^* \mathbf{r} = \mathbf{Q} \mathbf{r}$

IDR step

$$\mathcal{G}_{k} \xrightarrow{\rightarrow} \mathcal{G}_{k}^{\prime} \equiv \mathcal{G}_{k} \cap \widetilde{\mathbf{R}}^{\perp}$$
 pol. step
 $\mathbf{r}_{k} \xrightarrow{\Pi_{1}} \mathbf{r}_{k}^{\prime} \equiv \mathcal{G}_{k} \cap \widetilde{\mathbf{R}}^{\perp}$ $\overrightarrow{\mathbf{I}} \rightarrow \mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_{k} \mathbf{A}) \mathcal{G}_{k}^{\prime}$
 $\mathbf{r}_{k+1} = \mathbf{r}_{k}^{\prime} - \omega_{k} \mathbf{A} \mathbf{r}_{k}^{\prime}$
 $\Pi_{1} = \mathbf{I} - \mathbf{A} \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^{*}$ with $\sigma \equiv \mathbf{R}^{*} \mathbf{A} \mathbf{U}$ and $\mathbf{V} = \mathbf{A} \mathbf{U}$
 $\Pi_{1} = \mathbf{I} - \mathbf{A} \mathbf{Q}$ with $\mathbf{Q} \equiv \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^{*}$

Interpretation. Solve Au = r

Search for an approximate solution in $span(\mathbf{U})$

 $\mathbf{R}^* \mathbf{A} \mathbf{U} \alpha = \mathbf{R}^* \mathbf{r}$ Then $\mathbf{u} \approx \mathbf{U} \alpha = \mathbf{U} (\mathbf{R}^* \mathbf{A} \mathbf{U})^{-1} \mathbf{R}^* \mathbf{r} = \mathbf{Q} \mathbf{r}$

In multigrid:

 $\ensuremath{\mathsf{R}}^*$ represents the restriction operator

U represents the prolongation

 ${\boldsymbol{\mathsf{Q}}}$ is the coarse grid correction

IDR step

$$\mathcal{G}_{k} \xrightarrow{\rightarrow} \mathcal{G}_{k}^{\prime} \equiv \mathcal{G}_{k} \cap \widetilde{\mathbf{R}}^{\perp}$$
 pol. step
 $\mathbf{r}_{k} \xrightarrow{\Pi_{1}} \mathbf{r}_{k}^{\prime} \equiv \mathcal{G}_{k} \cap \widetilde{\mathbf{R}}^{\perp}$ $\xrightarrow{\rightarrow} \mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_{k} \mathbf{A}) \mathcal{G}_{k}^{\prime}$
 $\mathbf{r}_{k+1} = \mathbf{r}_{k}^{\prime} - \omega_{k} \mathbf{A} \mathbf{r}_{k}^{\prime}$
 $\Pi_{1} = \mathbf{I} - \mathbf{A} \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^{*}$ with $\sigma \equiv \mathbf{R}^{*} \mathbf{A} \mathbf{U}$ and $\mathbf{V} = \mathbf{A} \mathbf{U}$
 $\Pi_{1} = \mathbf{I} - \mathbf{A} \mathbf{Q}$ with $\mathbf{Q} \equiv \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^{*}$

Interpretation. Solve Au = r

Search for an approximate solution in span(U)

 $\mathbf{R}^* \mathbf{A} \mathbf{U} \alpha = \mathbf{R}^* \mathbf{r}$ Then $\mathbf{u} \approx \mathbf{U} \alpha = \mathbf{U} (\mathbf{R}^* \mathbf{A} \mathbf{U})^{-1} \mathbf{R}^* \mathbf{r} = \mathbf{Q} \mathbf{r}$

Then the update of the residual ${\boldsymbol{r}}$ is

$$\mathbf{r}_k' = \mathbf{r}_k - \mathbf{A}\mathbf{Q}\mathbf{r}_k$$

with update of the approximate solution

$$\mathbf{x}_k' = \mathbf{x}_k + \mathbf{Q}\mathbf{r}_k$$

IDR step

$$\mathcal{G}_k \xrightarrow{\rightarrow} \mathcal{G}'_k \equiv \mathcal{G}_k \cap \widetilde{\mathbf{R}}^{\perp}$$
 pol. step
 $\stackrel{\rightarrow}{\mathbf{r}_k} \mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_k \mathbf{A}) \mathcal{G}'_k$
 $\mathbf{r}_k = \Pi_1 \mathbf{r}_k$ $\mathbf{I} - \omega_k \mathbf{A}$
 $\mathbf{r}_{k+1} = \mathbf{r}'_k - \omega_k \mathbf{A} \mathbf{r}'_k$
 $\Pi_1 = \mathbf{I} - \mathbf{A} \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^*$ with $\sigma \equiv \mathbf{R}^* \mathbf{A} \mathbf{U}$ and $\mathbf{V} = \mathbf{A} \mathbf{U}$
 $\Pi_1 = \mathbf{I} - \mathbf{A} \mathbf{Q}$ with $\mathbf{Q} \equiv \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^*$

Coarse grid correction: $\mathbf{r}'_k = \mathbf{r}_k - \mathbf{A}\mathbf{Q}\mathbf{r}_k$ and $\mathbf{x}'_k = \mathbf{x}_k + \mathbf{Q}\mathbf{r}_k$ Smoothing: $\mathbf{r}_{k+1} = \mathbf{r}'_k - \omega \mathbf{A}\mathbf{r}'_k$ and $\mathbf{x}_{k+1} = \mathbf{x}'_k + \omega \mathbf{r}'_k$

IDR step

$$\mathcal{G}_k \rightarrow \mathcal{G}'_k \equiv \mathcal{G}_k \cap \widetilde{\mathbf{R}}^{\perp}$$
 pol. step
 $\mathbf{r}_k \cap \mathbf{I}_1$ $\mathbf{r}'_k = \Pi_1 \mathbf{r}_k$ $\mathbf{I} - \omega_k \mathbf{A}$ $\mathbf{r}_{k+1} \equiv (\mathbf{I} - \omega_k \mathbf{A}) \mathcal{G}'_k$
 $\mathbf{r}_k = \mathbf{I} - \mathbf{A} \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^*$ with $\sigma \equiv \mathbf{R}^* \mathbf{A} \mathbf{U}$ and $\mathbf{V} = \mathbf{A} \mathbf{U}$
 $\Pi_1 = \mathbf{I} - \mathbf{A} \mathbf{Q}$ with $\mathbf{Q} \equiv \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^*$

Coarse grid correction: $\mathbf{r}'_k = \mathbf{r}_k - \mathbf{A}\mathbf{Q}\mathbf{r}_k$ and $\mathbf{x}'_k = \mathbf{x}_k + \mathbf{Q}\mathbf{r}_k$ Smoothing: $\mathbf{r}_{k+1} = \mathbf{r}'_k - \omega \mathbf{A}\mathbf{r}'_k$ and $\mathbf{x}_{k+1} = \mathbf{x}'_k + \omega \mathbf{r}'_k$ Combine: $\mathbf{r}_{k+1} = (\mathbf{I} - \omega \mathbf{A})\Pi_1 \mathbf{r}_k = \mathbf{r}_k - \mathbf{A}(\mathbf{Q} + \omega \Pi_1)\mathbf{r}$ $\mathbf{x}_{k+1} = \mathbf{x}_k + (\mathbf{Q} + \omega \Pi_1)\mathbf{r}_k$ With $\mathbf{P} \equiv \mathbf{Q} + \omega \Pi$,

I – AP is the residual reduction operator

IDR step

$$\mathcal{G}_k \rightarrow \mathcal{G}'_k \equiv \mathcal{G}_k \cap \widetilde{\mathbf{R}}^{\perp}$$
 pol. step
 $\mathbf{r}_k \cap \mathbf{I}_1$ $\mathbf{r}'_k = \Pi_1 \mathbf{r}_k$ $\mathbf{I} - \omega_k \mathbf{A}$ $\mathbf{r}_{k+1} \equiv (\mathbf{I} - \omega_k \mathbf{A}) \mathcal{G}'_k$
 $\mathbf{r}_k = \mathbf{I} - \mathbf{A} \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^*$ with $\sigma \equiv \mathbf{R}^* \mathbf{A} \mathbf{U}$ and $\mathbf{V} = \mathbf{A} \mathbf{U}$
 $\Pi_1 = \mathbf{I} - \mathbf{A} \mathbf{Q}$ with $\mathbf{Q} \equiv \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^*$

Coarse grid correction: $\mathbf{r}'_k = \mathbf{r}_k - \mathbf{A}\mathbf{Q}\mathbf{r}_k$ and $\mathbf{x}'_k = \mathbf{x}_k + \mathbf{Q}\mathbf{r}_k$ Smoothing: $\mathbf{r}_{k+1} = \mathbf{r}'_k - \omega \mathbf{A}\mathbf{r}'_k$ and $\mathbf{x}_{k+1} = \mathbf{x}'_k + \omega \mathbf{r}'_k$ Combine: $\mathbf{r}_{k+1} = (\mathbf{I} - \omega \mathbf{A})\Pi_1 \mathbf{r}_k = \mathbf{r}_k - \mathbf{A}(\mathbf{Q} + \omega \Pi_1)\mathbf{r}$ $\mathbf{x}_{k+1} = \mathbf{x}_k + (\mathbf{Q} + \omega \Pi_1)\mathbf{r}_k$ With $\mathbf{P} \equiv \mathbf{Q} + \omega \Pi$,

I – PA is the error reduction operator

IDR step

$$\mathcal{G}_k \xrightarrow{\rightarrow} \mathcal{G}'_k \equiv \mathcal{G}_k \cap \widetilde{\mathbf{R}}^{\perp}$$
 pol. step
 $\stackrel{\rightarrow}{\mathbf{r}_k} \mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_k \mathbf{A}) \mathcal{G}'_k$
 $\mathbf{r}_k = \Pi_1 \mathbf{r}_k$ $\mathbf{I} - \omega_k \mathbf{A}$
 $\mathbf{r}_{k+1} = \mathbf{r}'_k - \omega_k \mathbf{A} \mathbf{r}'_k$
 $\Pi_1 = \mathbf{I} - \mathbf{A} \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^*$ with $\sigma \equiv \mathbf{R}^* \mathbf{A} \mathbf{U}$ and $\mathbf{V} = \mathbf{A} \mathbf{U}$
 $\Pi_1 = \mathbf{I} - \mathbf{A} \mathbf{Q}$ with $\mathbf{Q} \equiv \mathbf{U} \sigma^{-1} \widetilde{\mathbf{R}}^*$

Coarse grid correction: $\mathbf{r}'_k = \mathbf{r}_k - \mathbf{A}\mathbf{Q}\mathbf{r}_k$ and $\mathbf{x}'_k = \mathbf{x}_k + \mathbf{Q}\mathbf{r}_k$ Smoothing: $\mathbf{r}_{k+1} = \mathbf{r}'_k - \omega \mathbf{A}\mathbf{r}'_k$ and $\mathbf{x}_{k+1} = \mathbf{x}'_k + \omega \mathbf{r}'_k$ Combine: $\mathbf{r}_{k+1} = (\mathbf{I} - \omega \mathbf{A})\Pi_1 \mathbf{r}_k = \mathbf{r}_k - \mathbf{A}(\mathbf{Q} + \omega \Pi_1)\mathbf{r}$ $\mathbf{x}_{k+1} = \mathbf{x}_k + (\mathbf{Q} + \omega \Pi_1)\mathbf{r}_k$ With $\mathbf{P} \equiv \mathbf{Q} + \omega \Pi$,

$\boldsymbol{I}-\boldsymbol{\mathsf{P}}\boldsymbol{\mathsf{A}}$ is the error reduction operator

IDR can be viewed as

Richardson with a flexible preconditioner

Spectrum of IDR's error reduction operator

$$\Lambda(\mathbf{I} - \mathbf{P}\mathbf{A}) = \Lambda(\mathbf{I} - \mathbf{A}\mathbf{P}) = \Lambda(\Pi_1(\mathbf{I} - \omega\mathbf{A}))$$

The eigenvalues of the IDR error reduction operator

$\mathbf{I}-\mathbf{P}\mathbf{A}$

are related to the eigenvalues of the IDR deflated matrix

 $\Pi_1 \mathbf{A}$.

[Erlangga, Nabben, 2008]

Theorem. For a $\lambda \in \mathbb{C}, \lambda \neq 0$ we have that if $\Pi_1 \mathbf{A} \mathbf{v} = \lambda \mathbf{v}$ then $\Pi_1 (\mathbf{I} - \omega \mathbf{A}) \mathbf{v} = (1 - \omega \lambda) \mathbf{v}$ If $\Pi_1 \mathbf{A} \mathbf{v} = \mathbf{0}$ then $(\mathbf{I} - \mathbf{P} \mathbf{A}) \mathbf{v} = \mathbf{0}$.

With
$$(\omega_k)$$
, $P_{k+1}(\lambda) = (1 - \omega_k \lambda) P_k(\lambda)$,
 $\mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_k \mathbf{A}) \mathcal{G}'_k$ with $\mathcal{G}'_k \equiv \mathcal{G}_k \cap \mathbf{R}^{\perp}$,
Let \mathbf{V} be such that $\operatorname{span}(\mathbf{V}) \subset \mathcal{G}_k$ as in IDR

With
$$(\omega_k)$$
, $P_{k+1}(\lambda) = (1 - \omega_k \lambda) P_k(\lambda)$,
 $\mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_k \mathbf{A}) \mathcal{G}'_k$ with $\mathcal{G}'_k \equiv \mathcal{G}_k \cap \mathbf{R}^{\perp}$,

Let **V** be such that $\operatorname{span}(\mathbf{V}) \subset \mathcal{G}_k$

Theorem

- 0 is an eigenvalue of $\Pi_1 \mathbf{A}$ with geometric multiplicity $\geq s$.
- If $P_k(\mu) = 0$ (i.e., $\mu = 1/\omega_j$ for some j < k), then μ is an eigenvalue of $\Pi_1 \mathbf{A}$ with geometric multiplicity $\geq s$

• If
$$P_k(\mu) = P_k(\mu) = \ldots = P_k^{(\ell-1)}(\mu) = 0$$
 then

 μ is an eigenvalue of $\Pi_1 \mathbf{A}$ with algebraic multiplicity $\geq \ell s$ If $\operatorname{span}(\mathbf{V}) \subset \mathcal{G}_k$, then $\mathbf{V} = P_k(\mathbf{A}) \underline{\mathbf{V}}$ for some $n \times s$ matrix $\underline{\mathbf{V}} \perp \mathcal{K}_k(\mathbf{A}^*, \widetilde{\mathbf{R}})$.

• If
$$\widetilde{\mathbf{R}}^* (\mathbf{A} - \lambda \mathbf{I})^{-1} \mathbf{V}$$
 is singular,

then λ is an eigenvalue of $\Pi_1 \mathbf{A}$.

With
$$(\omega_k)$$
, $P_{k+1}(\lambda) = (1 - \omega_k \lambda) P_k(\lambda)$,
 $\mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_k \mathbf{A}) \mathcal{G}'_k$ with $\mathcal{G}'_k \equiv \mathcal{G}_k \cap \mathbf{R}^{\perp}$,

Let **V** be such that $\operatorname{span}(\mathbf{V}) \subset \mathcal{G}_k$

If $\operatorname{span}(\mathbf{V}) \subset \mathcal{G}_k$, then $\mathbf{V} = P_k(\mathbf{A})\underline{\mathbf{V}}$ for some $n \times s$ matrix $\underline{\mathbf{V}} \perp \mathcal{K}_k(\mathbf{A}^*, \widetilde{\mathbf{R}})$. **Theorem.** $\underline{\mathbf{V}}$ is independent of P_k in IDR.

With
$$(\omega_k)$$
, $P_{k+1}(\lambda) = (1 - \omega_k \lambda) P_k(\lambda)$,
 $\mathcal{G}_{k+1} \equiv (\mathbf{I} - \omega_k \mathbf{A}) \mathcal{G}'_k$ with $\mathcal{G}'_k \equiv \mathcal{G}_k \cap \mathbf{R}^{\perp}$,

Let \mathbf{V} be such that $\operatorname{span}(\mathbf{V})\subset \mathcal{G}_k$

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Though V_k has a "memory" of all ks vectors in the preceeding V_j (j < k): it allows control (clustering) of ks eigenvalues.

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Theorem

If P_k(μ) = 0 (i.e., μ = 1/ω_j for some j < k), then
 1 − ω_kμ is an eigenvalue of (**I** − ω_k**A**)Π₁ with multiplicity s,
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Comment. When selecting $\omega_j = 1$ $(j \le k)$,

0 is an eigenvalue of $(\mathbf{I} - \omega_k \mathbf{A}) \Pi_1$ with multiplicity (k+1)s.

With
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Theorem

- If P_k(μ) = 0 (i.e., μ = 1/ω_j for some j < k), then 1 − ω_kμ is an eigenvalue of (I − ω_kA)Π₁ with multiplicity s, 0 is an eigenvalue of (I − ω_kA)Π₁ with multiplicity s.
- If V_k is constructed with the IDR scheme, then the remaining n - (k + 1)s eigenvalues do not depend on ω_j , j < k.

Conclusions

- IDR is a [class of] very effective methods
- IDR can be viewed as a deflation method with a flexible preconditioner
- The deflated matrices as produced in IDR have remarkable spectral properties
- It is not clear how to exploit these elegant relations and properties to explain the effectiveness of IDR

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